

**LEMBAR  
HASIL PENILAIAN SEJAWAT SEBIDANG ATAU *PEER REVIEW*  
KARYA ILMIAH : PROSIDING INTERNASIONAL**

Judul Prosiding (Artikel) : Applied Drazin Inverse to Moore-Penrose inverse in rings with involution  
 Nama/ Jumlah Penulis : U Tarmizi, T Udjiani SRRM, **Susilo Hariyanto**, Harjito, F A Mansuri  
 Status Pengusul : penulis ke-3  
 Identitas Prosiding : a. Nama Prosiding : Journal of Physics: Conference Series  
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 f. Alamat web penerbit : <https://iopscience.iop.org/article/10.1088/1742-6596/1217/1/012069>  
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NIP. 195809011986032002  
Unit Kerja : FSM Undip  
Bidang Ilmu: Matematika

Reviewer 2

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Nama : Drs. Bayu Surarso, M.Sc Ph.D  
NIP. 19631105 198803 1 001  
Unit Kerja : FSM Undip  
Bidang Ilmu: Matematika

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Nama : Prof. Dr. Sunarsih, M.Si  
NIP. : 195809011986032002  
Unit Kerja : FSM Undip  
Bidang Ilmu: Matematika

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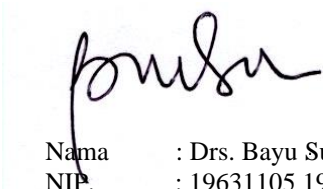
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**2. Ruang lingkup dan kedalaman pembahasan:**  
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**3. Kecukupan dan kemutakhiran data/informasi dan metodologi:**  
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**4. Kelengkapan unsur dan kualitas terbitan:**  
Terbitan baik dan unturnya lengkap. Artikel ini telah memenuhi standar publis di IOP. Hasil uji similaritas dengan turnitin juga baik, sebesar 16%.

Semarang, Februari 2023  
Reviewer 2



Nama : Drs. Bayu Surarso, M.Sc Ph.D  
NIP. : 19631105 198803 1 001  
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# Applied drazin inverse to moore-penrose inverse in rings with involution

[Tarmizi U.](#) ; [Udjiani Srrm T.](#); [Hariyanto S.](#); [Harjito](#); [Mansuri F.A.](#)

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<sup>a</sup> Department of Mathematics, Faculty of Science and Mathematics, Diponegoro University, Semarang, 50275, Indonesia

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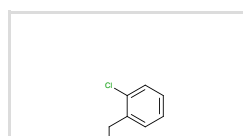
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The 8th International Seminar on New Paradigm and Innovation on Natural Sciences and Its Application (ISNPINSA-8) is annual seminars organized by Faculty of Sciences and Mathematics (FSM) Diponegoro University and has been successfully conducted since 2011. The ISNPINSA-8 was held in Semarang, Indonesia on September 26<sup>th</sup> 2018. The aims of ISNPINSA are to facilitate brain storming and state of the art information in field of sciences and mathematics; to increase innovation of technology that can be applied in industries; to contribute in formulating strategy to increase the role of science for community; and to stimulate collaboration between industries, researchers and government to increase community welfare. The theme of 8<sup>th</sup> ISNPINSA in 2018 is “*Science and Applied Science for Sustainable Development Goals*”.

The number of participants of the seminar were 272 including keynote speakers, invited speakers, oral presenters, poster presenters, and non presenters coming from various institutions of various countries, including Japan, Philippines, Thailand, Malaysia, Australia, Bangladesh, China, Kazakhtan, Vietnam and those who come from all parts of Indonesia consist of researchers, lecturers, postgraduate and undergraduate students from various universities. There are 272 papers were presented in this seminar, consist of 5 keynote speakers, 237 oral presentations, and 30 poster presentations. After the selection process, there are 184 articles selected papers to be published in the present conference proceeding. This is the largest number of papers and participants for eight times the implementation of ISNPINSA. The scope of the field of participants comes from various fields including biology, physics, chemistry, statistics, mathematics, informatics, environment, public health, and relevant fields that contribute to sustainable development.

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Prof. Dr. Kaemwich Jantama, Ph.D.	Suranaree University of Technology, Thailand
Prof. Dr. Hendrik Heijnis	Australian Nuclear Science and Technology, Australia
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Dr. Retno Kusumaningrum	Diponegoro University, Semarang, Indonesia
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Prof. Dr. Heri Sutanto	Diponegoro University, Semarang, Indonesia
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012073

## A combination of Rivest Shamir Adlemaan (RSA) and Affine Cipher method on improvement of the effectiveness and security of text message

# Growth and fabrication of 850 nm AlGaAs/GaAs vertical cavity surface emitting laser structure

**N I Cabello\*, P M Tingzon, H A Husay, J D Vasquez, R Jagus, K L Patrocenio, K C Gonzales, G A Catindig, E A Prieto, A Somintac, A Salvador and E Estacio**

National Institute of Physics, College of Science, University of the Philippines  
NIP Bldg, National Science Complex, Diliman, Quezon City 1101, Philippines  
E-mail: ncabello@nip.upd.edu.ph

**Abstract.** In this work, we demonstrate the NIP's all in-house development of a vertical cavity surface emitting laser structure. The VCSEL structure grown via MBE consists of an AlAs/AlGaAs distributed Bragg reflector and an AlGaAs/GaAs quantum well designed to issue at the 850 nm region. Reflectance spectroscopy showed that the stop band is centered around the designed wavelength. The electroluminescence spectra displayed that the maximum light emission corresponded to its design. This is a crucial step in the NIP's development of semiconductor lasers, leading towards future high-speed and highly-tunable VCSEL devices.

## 1. Introduction

Semiconductor lasers have been at the forefront of high-speed interconnects, thanks to the development of lasers capable of operating at gigahertz speeds [1]. Expansion to other applications such as proximity sensing [2] and light detection and ranging (LIDAR) [3] have driven further research on this field. For high-speed devices, switching speeds at the gigahertz range are desired [1], while high tuning speeds and increased tunability are sought for wavelength-tunable devices [4]. With its molecular beam epitaxy (MBE) and device fabrication facilities, the National Institute of Physics (NIP) has recently renewed its research thrust in this field, most notably on vertical cavity surface emitting lasers (VCSELs).

The VCSEL is a type of semiconductor laser with light emission orthogonal to the wafer plane. Its main advantages over other conventional semiconductor lasers such as edge-emitting lasers are the ease of coupling to optical fibers, direct wafer scale probing and low threshold operation [5]. A standard VCSEL design is composed of an optical cavity with an active region in the center, which is usually a quantum well (QW). The optical cavity is then sandwiched between two distributed Bragg reflectors (DBRs), which are highly reflecting mirrors composed of alternating high and low refractive index medium materials. The stop band of the DBR, which is the wavelength region with the highest reflectance, should coincide with the QW emission wavelength. Oxidation apertures, usually situated near the active region, are also employed for optical and current confinement [6].

In this paper, we report on the all in-house development of an AlGaAs/GaAs-based DBR VCSEL structure at the chip level. The whole process entails the whole production processes: the growth of the layers, device fabrication, and characterization of both as-grown and device-fabricated layers. Oxidation was also performed to explore the possibility of current and optical confinement effects [6].

## 2. Experimental Details



# Analysis of non-Newtonian lubricated textured contact for mixed slip/no-slip configuration considering cavitation

A W Pratomo<sup>1,2</sup>, Muhammad<sup>3</sup>, M Tauviquirrahman<sup>1</sup>, J Jamari<sup>1</sup> and A P Bayuseno<sup>1</sup>

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**Abstract.** The increasing use of non-Newtonian fluids as lubricants has received much attention due to their high shear. The present study explores a lubrication mechanism in lubricated textured contact for mixed slip/no-slip pattern considering cavitation. The effect of texturing depth on the bearing performance is also investigated. The numerical method based on commercial CFD (computational fluid dynamic) software is carried out to analyze the tribological characteristics (i.e., hydrodynamic pressure distribution) of lubricated textured contact. To model slip, the enhanced user-defined-function (UDF) in the FLUENT® package is developed. The analysis results show that giving textures as well as a slip to one of the parallel sliding surfaces can generate significant hydrodynamic pressure to affect the load support. The increase in the load support is also indicated by increasing the streamline recirculating flow. Besides, numerical results suggest that cavitation modeling has a significant effect on performance. Ignoring cavitation leads to less accurate results.

## 1. Introduction

The bearing has offered technological advances and has played an essential role in many relevant fields. However, the main problem limiting the development of the bearing extensively is friction and wear. To solve this problem, the use of artificial texture and slip is important in lubricated devices because of the benefits associated with load support and friction [1-2]. As a consequence of the development of modern machines, improved lubricant characteristics have received great attention. The researchers found the desired oil by adding some polymers to the Newtonian fluid, which in turn causes the fluid properties to be non-Newtonian. Experimental studies suggested that non-Newtonian fluids can improve lubrication performance in hydrodynamic bearing systems [3-4].

Recently, research on adding texture and slip on the bearings have been conducted by researchers [5-8]. Many researchers have also introduced an experimental work for the analysis of textured bearings with non-Newtonian lubricants [9-10]. In most existing studies, it is known that the width and/or height of texture and slip can increase the load and reduce friction. However, the consequence of growing load support causes changes in film thickness, causing changes in pressure on



# An investigation of a CT noise reduction using a modified of wiener filtering-edge detection

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**Abstract.** The aims of this study were to investigate the noise reduction in a CT image using a modified Wiener filtering-edge detection method. We modified the noise reduction algorithm of a combination of the Wiener filter and edge detection by addition of a dilation stage after edge detection. We then evaluated kernel size of the Wiener filter, threshold values in the edge detection, and size of structuring elements in the dilation process. Images of adult anthropomorphic and self-built wire phantoms were acquired by the new 4-row multislice CT Toshiba Alexion™. The images of the anthropomorphic phantom were used for a visual evaluation, while the images of the wire-phantom were used to obtain the spatial resolution and noise of the images. A Wiener filter-edge detection filter coupled with dilation, potentially reduced more CT noise. We found that the spatial resolution and noise of the filtered images were influenced by the size of the Wiener filter kernel, threshold of edge detection, and size of structuring element.

## 1. Introduction

Several approaches have been proposed to reduce CT dose without compromising image quality. One method has been proposed is the tube current modulation (TCM) [1, 2]. In TCM, tube currents decrease and increase proportionally with the decreasing and increasing attenuation of body parts [3]. Tube current modulation could be implemented by the rotation of the x-ray tube (angle-modulation) or by modulation in the direction of the longitudinal axis (Z-modulation), or a combination of both [4]. Another method proposed for reducing the dose is to utilize iterative reconstruction (IR) [5], instead of filtered back-projection (FBP). In fact, the IR technique is not only iterative during reconstruction but also iteratively processes in either the sinogram [6] or image spaces [7], in accordance with the specific physical modeling or statistical approaches. There are several IR software products used by major CT vendors including ASIR, AIDR, VEO, IRIS, SAFIRE, and iDose [8]. However, the details of the algorithms are very sparse, and they are still considered proprietary algorithms [5].

Another method that can be used for CT dose reduction is the use of noise reduction in the image space [8]. A noisy image due to acquisition with a small tube current-time (mAs) parameter can have





# Applied Drazin Inverse to Moore-Penrose inverse in rings with involution

*by* Susilo Hariyanto

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## Applied Drazin Inverse to Moore-Penrose inverse in rings with involution

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**Abstract.** Moore-Penrose inverse is one of development of generalized inverse. In this paper, we defined and studied a relation between the Moore-Penrose inverse and the Drazin inverse in the setting of rings with involution. The results of this paper are new characterizations of Moore-Penrose inverse by applying Drazin inverse with an algebraic proof.

### 1. Introduction

Moore-Penrose inverse was independently described by Moore (1920) and Penrose (1955). In numerical linear algebra, the Moore-Penrose inverse is commonly to find the matrix inverse of a singular matrix or rectangular matrix. Besides wide uses in the generalized matrix, Moore-Penrose inverse has also been applied in C\*-algebras (Harte, 1992), C\*-crosses product (Hiroyuki Osaka, 1998), and many more. Many types characteristic of Moore-Penrose Inverse has been found (Dragan S. Djordjevic, Pedro Particio, etc.). At this paper, we aimed to develop characteristics Moore-Penrose inverse in symmetric elements by Drazin inverse.

The paper is motivated by Mosaic and Djordjevic [2]. It was reported Moore-Penrose inverse had several characteristics including  $a^\dagger = (a^*a)^\dagger a^* = a^*(aa^*)^\dagger$  and  $(a^*)^\dagger = a(a^*a)^\dagger = (aa^*)^\dagger a$  and  $(aa^*a)^\dagger = a^\dagger(a^*)^\dagger a^\dagger$  that changed in the form of Drazin. Furthermore, the form of Drazin is applied to Moore-Penrose inverse with the symmetric rule.

Let  $R$  be a ring with identity and  $a \in R$ . An Involution “\*” in a ring is a unary operation  $a \rightarrow a^*$  such that :

$$(a^*)^* = a \quad (ab)^* = b^*a^* \quad (a+b)^* = a^*+b^*$$

for all elements  $a, b \in R$ . An element  $a \in R$  satisfying  $a = a^*$  is called Hermitian (or symmetric).

Let  $a \in R$  is said to be Moore-Penrose (MP) invertible with respect to “†”, if there exist  $a^\dagger \in R$  such that :

$$aa^\dagger a = a \quad a^\dagger aa^\dagger = a^\dagger \quad (aa^\dagger)^* = aa^\dagger \quad (a^\dagger a)^* = a^\dagger a$$

Also, the group inverse of  $a \in R$  exists if there is a  $a^\# \in R$  such that :

$$aa^\# a = a \quad a^\# aa^\# = a^\# \quad aa^\# = a^\# a$$



If the group inverse exists then it is unique.

An element  $a \in R$  is said to have a Drazin Inverse if there exists  $a^D \in R$  such that

$$a^D a a^D = a^D \quad a a^D = a^D a \quad a^{k+1} a^D = a^k, \text{ for some non-negative integer } k$$

If  $a \in R$  has a Drazin Inverse, then the smallest possible non-negative integer involve in (3) is called the Drazin index of  $a$ .

As for group inverse and Moore-Penrose inverse, if the Drazin inverse exists then it is unique.

## 2. Applied Drazin Inverse

In this section, we construct several lemmas that used to apply Drazin inverse to Moore Penrose inverse. In the paper of Koliha and Patricio [1] in theorem 5.4 said that Moore-Penrose invertible symmetric element is Drazin inverse. Based on that theorem, we applied Drazin inverse to Moore Penrose inverse that produces new characteristics. Before we apply Drazin inverse to Moore-Penrose inverse, we constructed some properties about Drazin inverse. The following lemma constructed by applied symmetric theorem in Drazin inverse. [4]

**Lemma 2.1** Let  $R$  be a ring with involution. If  $a \in R^\dagger$  then  $(a^D)^* = (a^*)^D$

**Proof** Let  $a \in R^\dagger$ , first

$$(a^D)^* a^* (a^D)^* = (a^D)^* (a^D a)^* = (a^D a a^D)^* = (a^D)^*,$$

second

$$a^* (a^D)^* = (a^D a)^* = (a a^D)^* = (a^D)^* a^*,$$

third

$$(a^{k+1})^* (a^D)^* = (a^D a^{k+1})^* = (a^{k+1} a^D)^* = (a^k)^*$$

We conclude that  $(a^D)^* = (a^*)^D$  ■

The following theorem lemma presents a relation between Moore-Penrose inverse and Drazin inverse.

**Theorem 2.2** [1] Let  $R$  be a ring with involution and  $a \in R^\dagger$ . If  $a^* = a$ , then  $a^\dagger = a^D$ .

**Proof.** Suppose  $a \in R^\dagger$  and  $a^* = a$ , first

$$a a^D a = a a a^D = a^2 a^D = a$$

second

$$a^D a a^D = a^D$$

third

$$(a a^D)^* = (a^D)^* a^* = a^D a = a a^D$$

fourth

$$(a^D a)^* = a^* (a^D)^* = a a^D = a^D a$$

Because all of the Moore-Penrose rules has been satisfied, so we can conclude that  $a^\dagger = a^D$ , if  $a^* = a$ . ■

Futhermore, we are modifying theorem 2.2 became to lemma 2.3.

**Lemma 2.3** Let  $R$  be a ring with involution. If  $a \in R^\dagger$ , then  $(a^* a)^\dagger = (a^* a)^D$ .

**Proof.** Let  $a \in R^\dagger$ , we get

$$a^* a (a^* a)^D a^* a = a^* a a^* (a^* a)^D a = a^* a a^* a (a^* a)^D = (a^* a)^2 (a^* a)^D = a^* a,$$

and

$$(a^* a)^D a^* a (a^* a)^D = (a^* a)^D,$$

also

$$\begin{aligned} \left( a^* a (a^* a)^D \right)^* &= \left( (a^* a)^D \right)^* (a^* a)^* = \left( (a^* a)^* \right)^D (a^* a)^* = \left( a^* (a^*)^* \right)^D a^* (a^*)^* = (a^* a)^D a^* a \\ &= a^* (a^* a)^D a = a^* a (a^* a)^D \end{aligned}$$

furthermore

$$\begin{aligned} \left( (a^* a)^D a^* a \right)^* &= (a^* a)^* \left( (a^* a)^D \right)^* = (a^* a)^* \left( (a^* a)^* \right)^D = a^* (a^*)^* \left( a^* (a^*)^* \right)^D = a^* a (a^* a)^D \\ &= a^* (a^* a)^D a = (a^* a)^D a^* a \end{aligned}$$

First rule, second rule, third rule, and fourth rule of Moore-Penrose inverse has been satisfied, we can conclude that  $(a^* a)^\dagger = (a^* a)^D$ . ■

Mosaic and Djordjevic [2] verified that  $a^\dagger = (a^* a)^\dagger a^* = a^* (aa^*)^\dagger$  in Theorem 1.2 (g). By using lemma 2.3 and Theorem 1.2 (g) in [2] we get Theorem 2.4.

**Theorem 2.4**

Let  $R$  be a ring with involution. If  $a \in R^\dagger$ , then  $a^\dagger = (a^* a)^D a^* = a^* (aa^*)^D$

**Proof.** Let  $a \in R^\dagger$ , we get

$$a^\dagger = a^\dagger aa^\dagger = a^\dagger (aa^\dagger)^* = a^\dagger (a^\dagger)^* a^* = (a^* a)^\dagger a^* = (a^* a)^D a^*$$

and

$$a^\dagger = a^\dagger aa^\dagger = (a^\dagger a)^* a^\dagger = a^* (a^\dagger)^* a^\dagger = a^* (aa^*)^\dagger = a^* (aa^*)^D$$

We conclude that  $a^\dagger = (a^* a)^D a^* = a^* (aa^*)^D$ . ■

Mosaic and Djordjevic said [2] reported that  $(a^*)^\dagger = a(a^* a)^\dagger = (aa^*)^\dagger a$  in Theorem 1.2 (h). By using Theorem 2.4 and Theorem 1.2 (h) in [2] on we get Theorem 2.5.

**Theorem 2.5**

Let  $R$  be a ring with involution. If  $a \in R^\dagger$ , then  $(a^*)^\dagger = a(a^* a)^D = (aa^*)^D a$

**Proof.** Let  $a \in R^\dagger$ , we get

$$\begin{aligned} (a^*)^\dagger &= a(a^* a)^\dagger = aa^\dagger (a^\dagger)^* = aa^\dagger (a^*)^\dagger = a(a^* a)^D a^* \left( a^* (a^*)^* \right)^D (a^*)^* = a(a^* a)^D a^* (a^* a)^D a \\ &= a(a^* a)^D a^* a (a^* a)^D = a(a^* a)^D \end{aligned}$$

and

$$\begin{aligned} (a^*)^\dagger &= (aa^*)^\dagger a = (a^\dagger)^* a^\dagger a = (a^*)^\dagger a^\dagger a = \left( (a^*)^* a^* \right)^D (a^*)^* (aa^*)^D a^\dagger a = (aa^*)^D a (aa^*)^D a^\dagger a \\ &= (aa^*)^D aa^* (aa^*)^D a = (aa^*)^D a \end{aligned}$$

We conclude that  $(a^*)^\dagger = a(a^* a)^D = (aa^*)^D a$ . ■

Mosaic and Djordjevic said in lemma 2.1 that  $(aa^* a)^\dagger = a^\dagger (a^*)^\dagger a^\dagger$ . By using Theorem 2.2 and lemma 2.1 in [2] we get Theorem 2.6.

**Theorem 2.6**

Let  $R$  be a ring with involution. If  $a \in R^\dagger$ , then  $(aa^*a)^\dagger = a^D(a^*)^D a^D$

**Proof.** Let  $a \in R^\dagger$ , we get

First

$$\begin{aligned} aa^*a(aa^*a)^D aa^*a &= aa^*aa^D(a^*)^D a^D aa^*a = aa^*a(a^*)^D a^D a^*a = a^2(a^*)^2(a^D)^* a^D a \\ &= a^2(a^D a^2)^* a^D a = a^2(a^*)^* a^D a = a^2 a^D a^* a = aa^*a \end{aligned}$$

Second

$$\begin{aligned} (aa^*a)^D aa^*a(aa^*a)^D &= a^D(a^*)^D a^D aa^*aa^D(a^*)^D a^D = (a^*)^D a^D aa^D a^* a^D aa^D(a^*)^D \\ &= (a^*)^D a^D a^* a^D(a^*)^D = a^D(a^D aa^D)^* a^D = a^D(a^D)^* a^D = a^D(a^*)^D a^D \end{aligned}$$

Third

$$\begin{aligned} (aa^*a(aa^*a)^D)^* &= (a^D(a^*)^D a^D)^* (aa^*a)^* = a^D(a^D)^* a^*(a^D)^* aa^* = a^D(a^D aa^D)^* aa^* = a^D(a^D)^* aa^* \\ &= aa^* a^D(a^*)^D = aa^* a^D aa^D(a^*)^D = aa^* aa^D(aa^*)^D = aa^* a(aa^*a)^D \end{aligned}$$

Fourth

$$\begin{aligned} ((aa^*a)^D aa^*a)^* &= (aa^*a)^* (a^D(a^*)^D a^D)^* = (a^D)^* a^*(a^D)^* (a^D(a^*)^D)^* = a^* a(a^D)^* a^*(a^D)^* a^D \\ &= a^* a(a^D aa^D)^* a^D = a^* a(a^D)^* a^D = (a^*)^D a^D a^* a = a^D(a^*)^D a^D aa^* a = (aa^*a)^D aa^* a \end{aligned}$$

So Moore-Penrose inverse has been satisfied, we can conclude that  $(aa^*a)^\dagger = a^D(a^*)^D a^D$  ■

**3. Conclusion**

Moore-Penrose inverse is very important in finding matrix inverse that singular matrix or rectangular matrix. There are many characters in Moore-Penrose inverse, but there is no developments in recent years. In this paper, we constructed new characteristic in Moore-Penrose by applied Drazin inverse in Moore-Penrose inverse with algebraic proof. The results are  $a^\dagger = (a^*a)^D a^* = a^*(aa^*)^D$  and  $(a^*)^\dagger = a(a^*a)^D = (aa^*)^D a$  also  $(aa^*a)^\dagger = a^D(a^*)^D a^D$ .

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