Bukti Korespondensi

Penulis : Muhammad Farouk Setiawan, **P. Paryanto***, Joga Dharma Setiawan

(Corresponding & 2nd author)

Jurnal : International Journal of Intelligent Robotics and Applications – Springer (Q2) –

SJR 2023: 0,59

Judul Paper : Simplified autonomous object grasping in material handling process

for human–robot collaboration

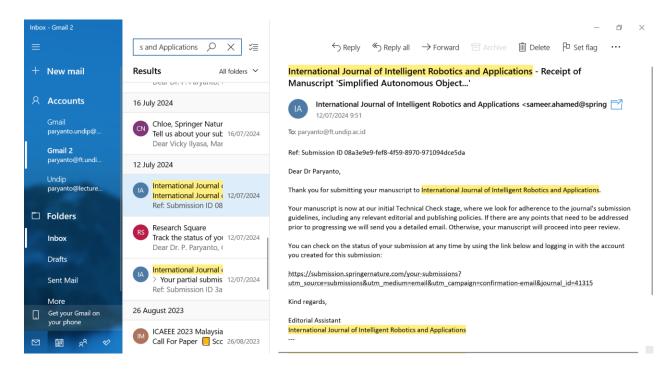
Link/DOI : https://doi.org/10.1007/s41315-024-00375-6

No	Jenis Korespondensi / Kegiatan	Tanggal	Lampiran bukti
1	Manuscript Submission to International	12 Juli 2024	Lampiran 1
	Journal of Intelligent Robotics and		
	Applications		
2	Decision on the manuscript: Major		Lampiran 2
	revisions	22 Juli 2024	
3	Response to Editor concerning	31 Juli 2024	Lampiran 3
	reviewer's feedback		
4	Acceptance of the manuscript after		Lampiran 4
	revision	09 Agustus 2024	
5	Article proofing	09 Agustus 2024	Lampiran 5
6	APC notification (free)	09 Agustus 2024	Lampiran 6
7	Publishing agreement	10 Agustus 2024	Lampiran 7
8	Paper online on Springer	28 Agustus 2024	Lampiran 8
9	Tracking paper submission history in	-	Lampiran 9
	Springer Nature		

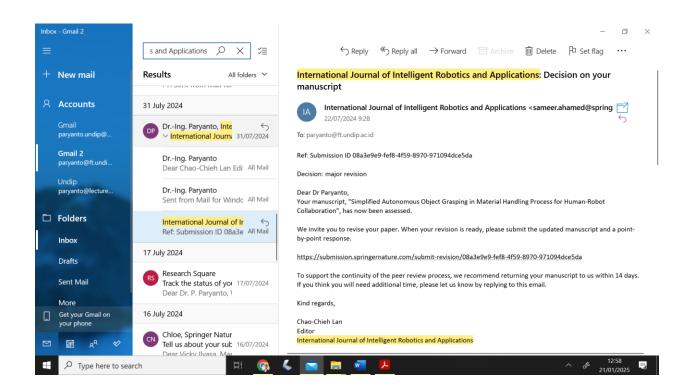
Semarang, 21.01.2024



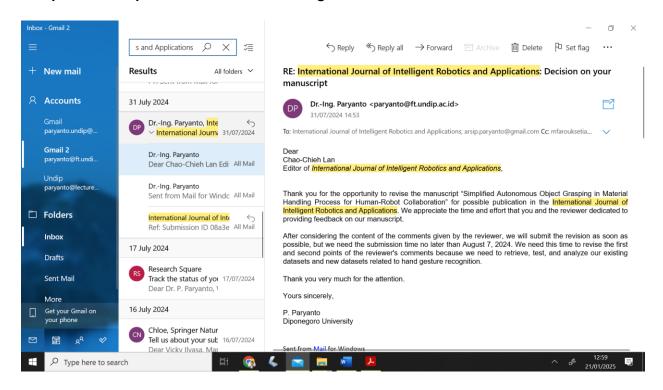
Lampiran 1: Manuscript Submission to International Journal of Intelligent Robotics and Applications – 12 Juli 2024



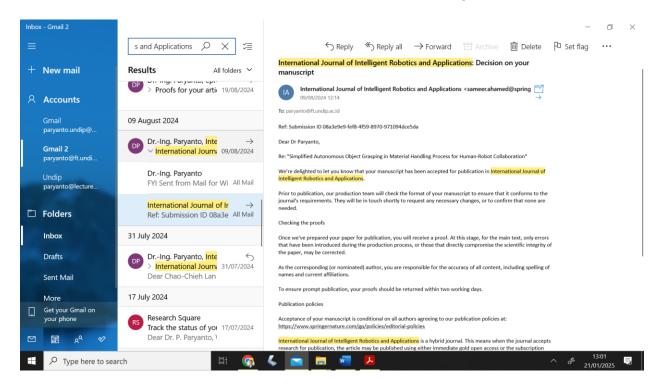
Lampiran 2: Decision on the manuscript: Major revisions - 22 Juli 2024



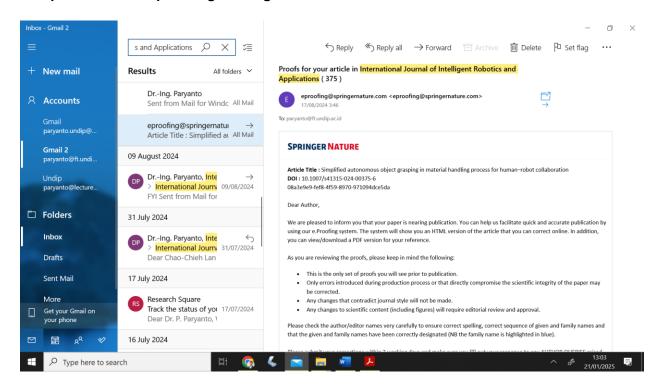
Lampiran 3: Response to Editor concerning reviewer's feedback - 31 Juli 2024



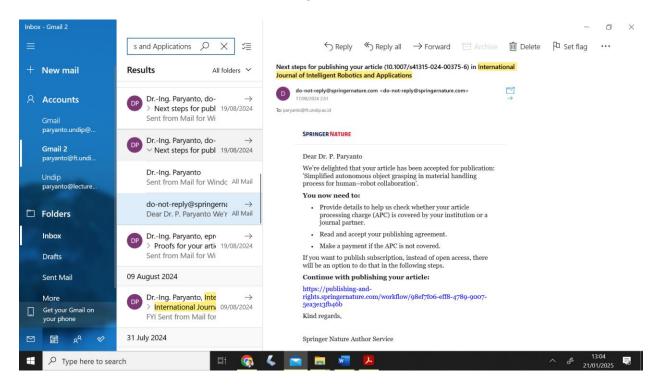
Lampiran 4: Acceptance of the manuscript after revision – 09 Agustus 2024



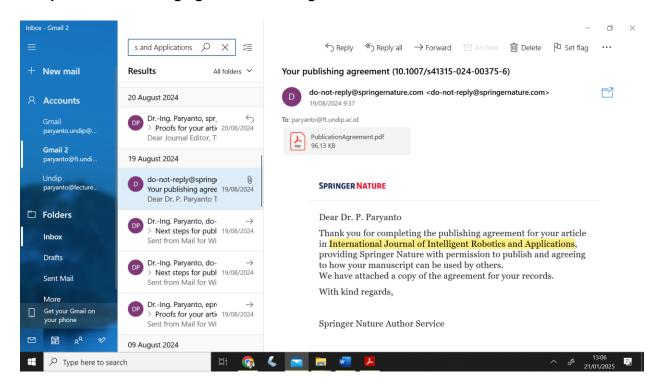
Lampiran 5: Article proofing - 09 Agustus 2024



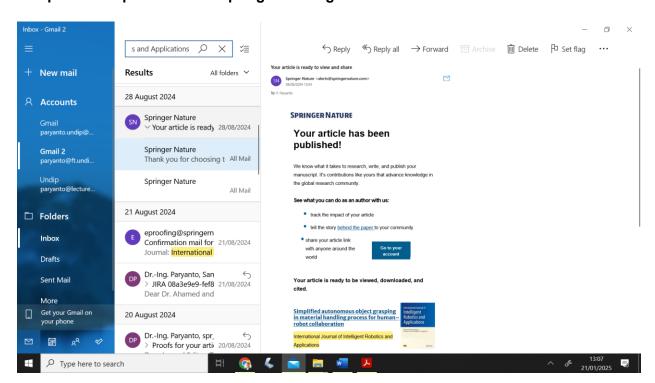
Lampiran 6: APC notification (free) - 09 Agustus 2024



Lampiran 7: Publishing agreement - 10 Agustus 2024



Lampiran 8: Paper online on Springer - 28 Agustus 2024





Lampiran 9: Tracking paper submission history in Springer Nature

