

Bukti Korespondensi

Penulis : Muhammad Farouk Setiawan, **P. Paryanto***, Joga Dharma Setiawan
(**Corresponding & 2nd author**)
Jurnal : *International Journal of Intelligent Robotics and Applications* – Springer (**Q2**) –
SJR 2023: 0,59
Judul Paper : *Simplified autonomous object grasping in material handling process
for human–robot collaboration*
Link/DOI : <https://doi.org/10.1007/s41315-024-00375-6>

No	Jenis Korespondensi / Kegiatan	Tanggal	Lampiran bukti
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Semarang, 21.01.2024



Lampiran 1: Manuscript Submission to International Journal of Intelligent Robotics and Applications – 12 Juli 2024

The screenshot shows a Gmail interface with a sidebar on the left containing 'Inbox - Gmail 2', 'New mail', 'Accounts', 'Folders', and 'More'. The main area displays a list of emails under the 'Results' tab. The selected email is from 'International Journal of Intelligent Robotics and Applications' dated 12/07/2024, with the subject 'Receipt of Manuscript 'Simplified Autonomous Object...'. The email body includes the journal's name, submission ID, and a thank you message for the submission.

Results All folders ▾

16 July 2024

Chloe, Springer Natur
Tell us about your sub: 16/07/2024
Dear Vicky Ilyasa, Mar

12 July 2024

International Journal of Intelligent Robotics and Applications
Ref: Submission ID 08 12/07/2024

Research Square
Track the status of your submission: 12/07/2024
Dear Dr. P. Paryanto, (

26 August 2023

ICAEEE 2023 Malaysia
Call For Paper 26/08/2023

International Journal of Intelligent Robotics and Applications - Receipt of Manuscript 'Simplified Autonomous Object...'

International Journal of Intelligent Robotics and Applications <sameer.ahamed@springer.com>
12/07/2024 9:51

To: paryanto@ft.undip.ac.id

Ref: Submission ID 08a3e9e9-fef8-4f59-8970-971094dce5da

Dear Dr Paryanto,

Thank you for submitting your manuscript to **International Journal of Intelligent Robotics and Applications**.

Your manuscript is now at our initial Technical Check stage, where we look for adherence to the journal's submission guidelines, including any relevant editorial and publishing policies. If there are any points that need to be addressed prior to progressing we will send you a detailed email. Otherwise, your manuscript will proceed into peer review.

You can check on the status of your submission at any time by using the link below and logging in with the account you created for this submission:

https://submission.springernature.com/your-submissions?utm_source=submissions&utm_medium=email&utm_campaign=confirmation-email&Journal_id=41315

Kind regards,

Editorial Assistant
International Journal of Intelligent Robotics and Applications

Lampiran 2: Decision on the manuscript: Major revisions – 22 Juli 2024

The screenshot shows a Gmail interface with a sidebar on the left containing 'Inbox - Gmail 2', 'New mail', 'Accounts', 'Folders', and 'More'. The main area displays a list of emails under the 'Results' tab. The selected email is from 'International Journal of Intelligent Robotics and Applications' dated 22/07/2024, with the subject 'Decision on your manuscript'. The email body includes the journal's name, submission ID, and a decision to request major revisions.

Results All folders ▾

31 July 2024

Dr.-Ing. Paryanto, International Journal of Intelligent Robotics and Applications
31/07/2024

Dr.-Ing. Paryanto
Dear Chao-Chieh Lan Editor: All Mail

Dr.-Ing. Paryanto
Sent from Mail for Windows: All Mail

International Journal of Intelligent Robotics and Applications
Ref: Submission ID 08a3e9e9-fef8-4f59-8970-971094dce5da All Mail

17 July 2024

Research Square
Track the status of your submission: 17/07/2024
Dear Dr. P. Paryanto, (

16 July 2024

Chloe, Springer Natur
Tell us about your submission: 16/07/2024
Dear Vicky Ilyasa, Mar

International Journal of Intelligent Robotics and Applications: Decision on your manuscript

International Journal of Intelligent Robotics and Applications <sameer.ahamed@springer.com>
22/07/2024 9:28

To: paryanto@ft.undip.ac.id

Ref: Submission ID 08a3e9e9-fef8-4f59-8970-971094dce5da

Decision: major revision

Dear Dr Paryanto,

Your manuscript, "Simplified Autonomous Object Grasping in Material Handling Process for Human-Robot Collaboration", has now been assessed.

We invite you to revise your paper. When your revision is ready, please submit the updated manuscript and a point-by-point response.

<https://submission.springernature.com/submit-revision/08a3e9e9-fef8-4f59-8970-971094dce5da>

To support the continuity of the peer review process, we recommend returning your manuscript to us within 14 days. If you think you will need additional time, please let us know by replying to this email.

Kind regards,

Chao-Chieh Lan
Editor
International Journal of Intelligent Robotics and Applications

Lampiran 3: Response to Editor concerning reviewer's feedback – 31 Juli 2024

The screenshot shows a Gmail interface with a sidebar on the left containing 'New mail', 'Accounts', 'Folders', and 'Inbox'. The main area displays a list of emails. The selected email is from Dr.-Ing. Paryanto to the International Journal of Intelligent Robotics and Applications, dated 31/07/2024. The email body contains a response to the editor, Chao-Chieh Lan, regarding a manuscript revision. The response includes a thank you for the opportunity to revise, a statement of intent to submit the revision by August 7, 2024, and a closing signature from P. Paryanto at Diponegoro University.

Results All folders ▾

31 July 2024

DP Dr.-Ing. Paryanto, Inte International Journ 31/07/2024

Dr.-Ing. Paryanto
Dear Chao-Chieh Lan Edi All Mail

Dr.-Ing. Paryanto
Sent from Mail for Windo All Mail

International Journal of Inte
Ref: Submission ID 08a3e All Mail

17 July 2024

RS Research Square
Track the status of yo 17/07/2024
Dear Dr. P. Paryanto, 1

16 July 2024

CN Chloe, Springer Natur
Tell us about your sut 16/07/2024
Dear Vicky Ilvasa, Mar

RE: **International Journal of Intelligent Robotics and Applications: Decision on your manuscript**

DP Dr.-Ing. Paryanto <paryanto@ft.undip.ac.id>
31/07/2024 14:53

To: International Journal of Intelligent Robotics and Applications; arsip.paryanto@gmail.com Cc: mfarouksetia...

Dear
Chao-Chieh Lan
Editor of **International Journal of Intelligent Robotics and Applications**.

Thank you for the opportunity to revise the manuscript "Simplified Autonomous Object Grasping in Material Handling Process for Human-Robot Collaboration" for possible publication in the **International Journal of Intelligent Robotics and Applications**. We appreciate the time and effort that you and the reviewer dedicated to providing feedback on our manuscript.

After considering the content of the comments given by the reviewer, we will submit the revision as soon as possible, but we need the submission time no later than August 7, 2024. We need this time to revise the first and second points of the reviewer's comments because we need to retrieve, test, and analyze our existing datasets and new datasets related to hand gesture recognition.

Thank you very much for the attention.

Yours sincerely,
P. Paryanto
Diponegoro University

Sent from Mail for Windows

Lampiran 4: Acceptance of the manuscript after revision – 09 Agustus 2024

The screenshot shows a Gmail interface with a sidebar on the left containing 'New mail', 'Accounts', 'Folders', and 'Inbox'. The main area displays a list of emails. The selected email is from the International Journal of Intelligent Robotics and Applications to Dr.-Ing. Paryanto, dated 09/08/2024. The email body contains a message of acceptance for publication, detailing the next steps for proof submission and publication policies.

Results All folders ▾

DP Dr.-Ing. Paryanto, Inte International Journ 09/08/2024

Dr.-Ing. Paryanto
FYI Sent from Mail for Wi All Mail

International Journal of Ir
Ref: Submission ID 08a3e All Mail

31 July 2024

DP Dr.-Ing. Paryanto, Inte International Journ 31/07/2024
Dear Chao-Chieh Lan

17 July 2024

RS Research Square
Track the status of yo 17/07/2024
Dear Dr. P. Paryanto, 1

International Journal of Intelligent Robotics and Applications: Decision on your manuscript

IA International Journal of Intelligent Robotics and Applications <sameer.ahamed@spring 09/08/2024 12:14

To: paryanto@ft.undip.ac.id

Ref: Submission ID 08a3e9ef8-fef8-4f59-8970-971094dce5da

Dear Dr Paryanto,

Re: "Simplified Autonomous Object Grasping in Material Handling Process for Human-Robot Collaboration"

We're delighted to let you know that your manuscript has been accepted for publication in **International Journal of Intelligent Robotics and Applications**.

Prior to publication, our production team will check the format of your manuscript to ensure that it conforms to the journal's requirements. They will be in touch shortly to request any necessary changes, or to confirm that none are needed.

Checking the proofs

Once we've prepared your paper for publication, you will receive a proof. At this stage, for the main text, only errors that have been introduced during the production process, or those that directly compromise the scientific integrity of the paper, may be corrected.

As the corresponding (or nominated) author, you are responsible for the accuracy of all content, including spelling of names and current affiliations.

To ensure prompt publication, your proofs should be returned within two working days.

Publication policies

Acceptance of your manuscript is conditional on all authors agreeing to our publication policies at: <https://www.springernature.com/gp/policies/editorial-policies>

International Journal of Intelligent Robotics and Applications is a hybrid journal. This means when the journal accepts research for publication, the article may be published using either immediate gold open access or the subscription

Lampiran 5: Article proofing – 09 Agustus 2024

The screenshot shows a Gmail interface with a sidebar on the left containing 'New mail', 'Accounts', 'Folders', and 'More'. The main area displays a list of emails. The selected email is from 'eproofing@springernature.com' dated 17/08/2024, titled 'Proofs for your article in International Journal of Intelligent Robotics and Applications (375)'. The email body features the Springer Nature logo and the following text:

Article Title: Simplified autonomous object grasping in material handling process for human–robot collaboration
DOI: 10.1007/s41315-024-00375-6
08a3e9e9-fe8-4f59-8970-971094dce5da

Dear Author,

We are pleased to inform you that your paper is nearing publication. You can help us facilitate quick and accurate publication by using our e.Proofing system. The system will show you an HTML version of the article that you can correct online. In addition, you can view/download a PDF version for your reference.

As you are reviewing the proofs, please keep in mind the following:

- This is the only set of proofs you will see prior to publication.
- Only errors introduced during production process or that directly compromise the scientific integrity of the paper may be corrected.
- Any changes that contradict journal style will not be made.
- Any changes to scientific content (including figures) will require editorial review and approval.

Please check the author/editor names very carefully to ensure correct spelling, correct sequence of given and family names and that the given and family names have been correctly designated (NB the family name is highlighted in blue).

Lampiran 6: APC notification (free) - 09 Agustus 2024

The screenshot shows a Gmail interface with a sidebar on the left. The main area displays a list of emails. The selected email is from 'do-not-reply@springernature.com' dated 17/08/2024, titled 'Next steps for publishing your article (10.1007/s41315-024-00375-6) in International Journal of Intelligent Robotics and Applications'. The email body features the Springer Nature logo and the following text:

Dear Dr. P. Paryanto

We're delighted that your article has been accepted for publication: 'Simplified autonomous object grasping in material handling process for human–robot collaboration'.

You now need to:

- Provide details to help us check whether your article processing charge (APC) is covered by your institution or a journal partner.
- Read and accept your publishing agreement.
- Make a payment if the APC is not covered.

If you want to publish subscription, instead of open access, there will be an option to do that in the following steps.

Continue with publishing your article:

<https://publishing-and-rights.springernature.com/workflow/98ef7f06-eff8-4789-9007-5ea3e13fb46b>

Kind regards,

Springer Nature Author Service

Lampiran 7: Publishing agreement – 10 Agustus 2024

The screenshot shows a Gmail interface on a Windows desktop. The left sidebar displays the 'Inbox - Gmail 2' with a search bar containing 's and Applications'. The main inbox area shows a list of emails from August 2024. The selected email is from 'do-not-reply@springernature.com' dated 19/08/2024, titled 'Your publishing agreement (10.1007/s41315-024-00375-6)'. The email content includes the Springer Nature logo, a greeting to Dr. P. Paryanto, a thank you for completing the publishing agreement for the article 'Simplified autonomous object grasping in material handling process for human-robot collaboration' in the 'International Journal of Intelligent Robotics and Applications', and an attached PDF file named 'PublicationAgreement.pdf' (96,13 KB). The email is signed by the Springer Nature Author Service.

Results All folders ▾

20 August 2024

DP Dr.-Ing. Paryanto, spr...
> Proofs for your arti... 20/08/2024
Dear Journal Editor, T

19 August 2024

D do-not-reply@spring...
Your publishing agree... 19/08/2024
Dear Dr. P. Paryanto T

DP Dr.-Ing. Paryanto, do-...
> Next steps for publ... 19/08/2024
Sent from Mail for Wi

DP Dr.-Ing. Paryanto, do-...
> Next steps for publ... 19/08/2024
Sent from Mail for Wi

DP Dr.-Ing. Paryanto, epr...
> Proofs for your arti... 19/08/2024
Sent from Mail for Wi

09 August 2024

Your publishing agreement (10.1007/s41315-024-00375-6)

do-not-reply@springernature.com <do-not-reply@springernature.com>
19/08/2024 9:37

To: paryanto@ft.undip.ac.id

PublicationAgreement.pdf
96,13 KB

SPRINGER NATURE

Dear Dr. P. Paryanto

Thank you for completing the publishing agreement for your article in **International Journal of Intelligent Robotics and Applications**, providing Springer Nature with permission to publish and agreeing to how your manuscript can be used by others.

We have attached a copy of the agreement for your records.

With kind regards,

Springer Nature Author Service

Lampiran 8: Paper online on Springer – 28 Agustus 2024

The screenshot shows a Gmail interface on a Windows desktop. The left sidebar displays the 'Inbox - Gmail 2' with a search bar containing 's and Applications'. The main inbox area shows a list of emails from August 2024. The selected email is from 'Springer Nature' dated 28/08/2024, titled 'Your article has been published!'. The email content includes the Springer Nature logo, a confirmation that the article is ready to view and share, and a link to the article. The article title is 'Simplified autonomous object grasping in material handling process for human-robot collaboration' in the 'International Journal of Intelligent Robotics and Applications'. The email is signed by the Springer Nature Author Service.

Results All folders ▾

28 August 2024

SN Springer Nature
✓ Your article is ready 28/08/2024

Springer Nature
Thank you for choosing t All Mail

Springer Nature
All Mail

21 August 2024

E eproofing@springern...
Confirmation mail for... 21/08/2024
Journal: **International**

DP Dr.-Ing. Paryanto, San...
> JIRA 08a3e9e9-fef8 21/08/2024
Dear Dr. Ahamed and

20 August 2024

DP Dr.-Ing. Paryanto, spr...
> Proofs for your arti... 20/08/2024

Your article is ready to view and share

Springer Nature <alerts@springernature.com>
28/08/2024 10:43

To: P. Paryanto

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[Simplified autonomous object grasping in material handling process for human-robot collaboration](#)

[International Journal of Intelligent Robotics and Applications](#)

← → ↻ <https://link.springer.com/article/10.1007/s41315-024-00375-6#citeas> 🔍 ☆ 📄 📌 👤 ⋮
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Simplified autonomous object grasping in material handling process for human–robot collaboration

Regular Paper | Published: 28 August 2024
(2024) [Cite this article](#)



International Journal of Intelligent Robotics and Applications

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Muhammad Farouk Setiawan, [P. Paryanto](#) ✉ & [Joga Dharma Setiawan](#)

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Abstract

The application of Human–Robot Collaboration (HRC) in the manufacturing sector, especially in the material handling process, is aimed at improving productivity through robots actively working alongside humans. In this condition, the robots need to understand how to handle the objects by themselves according to user preferences with an

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Lampiran 9: Tracking paper submission history in Springer Nature

Submission Details : International > +

← → ↻ https://submission.springernature.com/submission-details/08a3e9e9-fef8-4f59-8970-971094dce5da?_gl=1*lllu9g*_ga*ODc3NDM2OC4xNzE2NDI... ☆ 📄 📌 👤 ⋮
📖 All Bookmarks

CURRENT STATUS

We've sent your submission

Our production department will process your submission. They will email you when it is ready for publication.

Need help?

If you have any questions about this submission, please contact your editor or publisher.

For general enquiries, please look at our [FAQ](#).

Submission history

Submission received	
Submission received	12 Jul 2024
Technical check	
Submission is under technical check	12 Jul 2024
Submission passed technical check	12 Jul 2024
Editorial assignment	
Ready for editorial assignment	12 Jul 2024
With editor	
Editor assigned	14 Jul 2024

...ss so far [Show history](#)

Submission received

Technical check

Editorial assignment

With editor

Review

Submission accepted

Publishing and rights

Production

[Follow our submission process](#)

Submission

Windows taskbar: Type here to search, 13:13, 21/01/2025

Submission Details : International

https://submission.springernature.com/submission-details/08a3e9e9-fef8-4f59-8970-971094dce5da?_gl=1*llu9g*_ga*ODc3NDM2OC4xNzE2NDI...

CURRENT STATUS

We've sent your submission

Our production department will process your submission. They will email you when it is ready for publication.

Need help?

If you have any questions about this submission, please contact your journal editor or the Springer Nature Customer Service Center.

For general enquiries, please look at our frequently asked questions.

Submission history

Status	Date
Ready for editorial assignment	12 Jul 2024
With editor	
Editor assigned	14 Jul 2024
Peer review	
First reviewer(s) invited	14 Jul 2024
Reviewer(s) accepted	15 Jul 2024
Reviewer report(s) received	20 Jul 2024
Revision requested	22 Jul 2024
Revision received	06 Aug 2024
Submission passed technical check	07 Aug 2024
First reviewer(s) invited	08 Aug 2024

13:14 21/01/2025

Submission Details : International

https://submission.springernature.com/submission-details/08a3e9e9-fef8-4f59-8970-971094dce5da?_gl=1*llu9g*_ga*ODc3NDM2OC4xNzE2NDI...

CURRENT STATUS

We've sent your submission

Our production department will process your submission. They will email you when it is ready for publication.

Need help?

If you have any questions about this submission, please contact your journal editor or the Springer Nature Customer Service Center.

For general enquiries, please look at our frequently asked questions.

Submission history

First reviewer(s) invited	08 Aug 2024
Reviewer(s) accepted	09 Aug 2024
Reviewer report(s) received	09 Aug 2024
Submission accepted	
Submission accepted	09 Aug 2024
Publishing and rights	
Submission is in publishing and rights	16 Aug 2024
Production	
Publishing and rights complete	19 Aug 2024

13:14 21/01/2025